





# ELECTRO-PNEUMATIC POSITIONERS TZIDC

## **DESCRIPTION**

The ADCATrol TZIDC is a digital intelligent electronically configurable positioner with communication capabilities designed for mounting to pneumatic linear or rotary actuators. It features a small and compact design, a modular construction, and an excellent cost-performance ratio.

Fully automatic determination of the control parameters and adaptation to the final control element yield considerable time savings and an optimal control behaviour.



## MAIN FEATURES

Low operating cost.

Compact and flexible design.

Easy to comission with user-friendly interface.

Increased shock and vibration resistance with gearless sensor activation.

Reliable and efficient, with integrated maintenance-friendly air filters.

Automatic adjustment of control parameters during operation.

Integrated mechanical position indicator.

With HART, Profibus PA or FOUNDATION Fieldbus-H1.

Wide operating temperature range (- 40 ° to 85 °C).

Mounting onto any linear or rotary actuator.

Single or double acting.

ATEX, FM, CSA, GOST and IECEx approvals.

For SIL2 safety loops.

## **OPTIONS AND ACCESSORIES**

Module for analog position feedback.

Digital position feedback with inductive proximity switches.

Digital position feedback with 24 V microswitches.

Positioner with remote sensor.

Attachment kit for linear actuators acc. to IEC 534/NAMUR and rotary actuators acc. to VDI/VDE 3845.

Connection manifold with gauges.

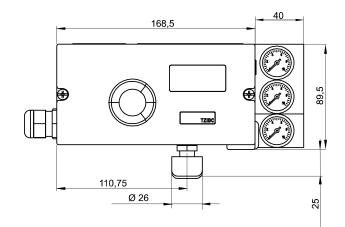
PC adapters for communication.

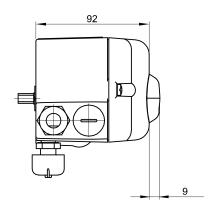
PC software for remote configuration and operation.

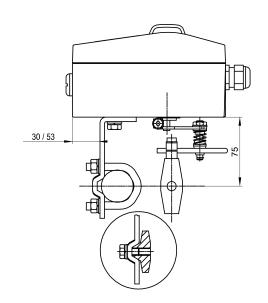


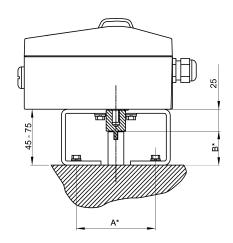


## **DIMENSIONS (mm)**









 $^{\star}$  Dimensions A and B are dependent on the rotary actuator.

## **TECHNICAL DATA**

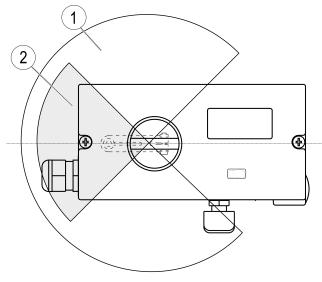
GENERAL		
Material	Aluminum with ≤ 0.1% copper	
IP rating	Protection class IP 65 (IP 66 on request) NEMA 4X	
Surface	Electrostatic dipping varnish with epoxy resin, stove-hardened	
Pneumatic connections	Female threaded ISO 228 G 1/4"	
Electrical connections	M20 x 1,5 Cable glands Screw terminals: max. 1.0 mm² for options max. 2.5 mm² for bus connector	
Weight	1,7 kg	
Mounting orientation	Any	

DIRECTIVES AND COMMUNICATION		
Directives	Compliant with: - EMC directive 2004/108/EC from 12/2004 - EC Directive for CE conformity marking	
Communication	- HART® protocol 5.9 as standard, optionally HART® protocol 7.4  - Profibus PA  - FOUNDATION Fieldbus H1  - Local connector for LCI (not in explosion protection area)  - HART communication via 20 mA signal line with (optional) FSK modem	





TRAVEL		
Rotation angle		
Measuring range	270°	
Working range	Linear actuators: min. 25°, max. 45°	
(Fig.1)	Rotary actuators: min. 25°, max. <270°	
Travel limit	Min. and max. limits, freely configurable between 0 to 100 % of total travel (min. range > 20 %)	
Travel prolongation	Range of 0 to 200 s, separately for each direction	
Dead band time limit	Setting range of 0 to 200 s (monitoring parameter for control until the deviation reaches the dead band)	



- 1 Measuring range
- 2 Operating range

Fig. 1 - Measuring and operating ranges

AIR SUPPLY *		
Instrument air		
Purity	Max. particle size: 5 µm Max. particle density: 5 mg / m³	
Oil content	Max. concentration: 1 mg / m³	
Pressure dew point	10 K below operating temp	
Supply pressure **	1.4 to 6 bar	
Air consumption ***	< 0.03 kg/h / 0.015 scfm	
* Frog of oil water and dust according to DIN/ISO 9573 1 Pollution and		

<sup>\*</sup> Free of oil, water and dust, according to DIN/ISO 8573-1. Pollution and oil content according to Class 3.

TRANSMISSION DATA AND CONTRIBUTING FACTORS		
Output Y1		
Increasing	Increasing setpoint signal 0 to 100% Increasing pressure at output	
Decreasing	Increasing setpoint signal 0to100% Decreasing pressure at output	
Action (setpoint signal)		
Increasing	Signal 4 to 20 mA = Position 0 to 100%	
Decreasing	Signal 20 to 4 mA = Position 0 to 100%	
Characteristic curve (travel = f {setpoint signal}) *		
Deviation	≤ 0.5 %	
Tolerance band	0,3 to 10 %, adjustable	
Dead band	0,1 to 10 %, adjustable	
Resolution (A/D conversion)	> 16,000 steps	
Sample rate	20 ms	
Influence of ambient temp.	≤ 0.5 % per 10 K	
Reference temperature	20 °C	
Influence of vibration	≤ 1 % to 10 g and 80 Hz	
Seismic vibration	Meets requirements of DIN/IEC 68-3-3 Class III for strong and strongest earthquakes	

<sup>\*</sup> Linear, equal percentage 1:25 or 1:50 or 25:1 or 50:1 and freely configurable with 20 reference points

AMBIENT CONDITIONS		
Ambient temperature		
During operation, storage and transport	- 40 °C to 85 °C - 25 °C to 85 °C - 40 °C to 100 °C *	
Relative humidity		
Operation (closed housing and air supply switched on)	95 % (annual average), condensation permissible	
Transport and storage	75% (annual average), non-condensing.	

<sup>\*</sup> Increased temperature range only with TZIDC Remote Sensor.

SAFETY INTEGRITY LEVEL		
the following	- Functional safety acc. to IEC 61508 - Explosion protection (depending on the model) - Electromagnetic compatibility acc. to EN 61000	

Without the input signal, the pneumatic module in the positioner vents the drive and the installed spring in it moves the valve to a predetermined end position (OPEN or CLOSED).

SIL specific safety-related characteristics				
Device	SFF	PFDav	$\lambda_{dd} + \lambda_{s}$	λ <sub>du</sub>
TZDIC with supply current 0 mA	94%	1.76 x 10⁴	651 FIT	40 FIT

Remarks: Applies to applications with single-acting and depressurizing pneumatics.

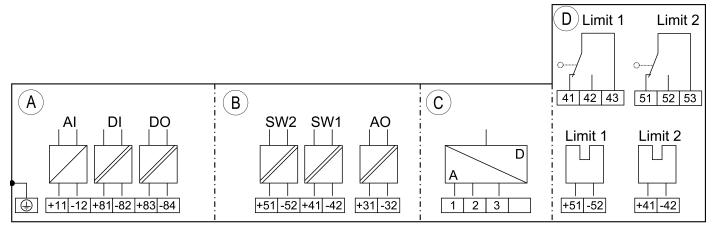
<sup>\*\*</sup> Do not exceed the maximum operating pressure of the actuator!

<sup>\*\*\*</sup> Independent of supply pressure.





## ELECTRICAL CONNECTIONS Positioner / TZIDC control unit connections



A Basic device

B Options

$\left( \mathbf{C}\right)$	(only for TZIDC Control Unit version)
$\bigcirc$	Limit value monitor with proximity switches or microswitches (not for TZIDC Control Unit version)

Connection TZIDC Remote Sensor / remote position sensor

TERMINALS		
TERMINAL	DESCRIPTION	
+11 / -12	Analog input	
+81 / -82	Binary input DI	
+83 / -84	Binary output DO2	
+51 / -52	Digital feedback SW1 (optional module)	
+41 / -42	Digital feedback SW2 (optional module)	
+31 / -32	Analog feedback AO (optional module)	
1/2/3	TZDIC remote sensor *	
+51 / -52	Limit switch Limit 1 with proximity switch (optional)	
+41 / -42	Limit switch Limit 2 with proximity switch (optional)	
41 / 42 / 43	Limit switch Limit 1 with microswitch (optional)	
51 / 52 / 53	Limit switch Limit 2 with microswitch (optional)	

<sup>\*</sup> Only for options TZIDC Remote Sensor or TZIDC for remote position sensor.

Remarks: The TZIDC can be fitted either with proximity switches or microswitches as limit switches. It is not possible to combine both variants. For the version TZIDC Control Unit with TZIDC Remote Sensor, the limit switches are located in the TZIDC Remote Sensor.

Binary output DO *		
Terminals	+83 / -84	
Supply voltage	5 to 11 V DC (Control circuit in accordance with DIN 19234 / NAMUR)	
Output "logical 0"	> 0,35 mA to < 1,2 mA	
Output "logical 1"	> 2,1 mA	
Direction of action	Configurable "logical 0" or "logical 1"	

<sup>\*</sup> Output configurable as alarm output by software.

ANALOG INPUT SIGNAL		
Set point signal (two-wire technology)		
Terminals	+11 / -12	
Nominal operating range	4 to 20 mA	
Split range config.	between 20 to 100% of the nominal operating range can be parameterized	
Operating range limits	3.8 to 50 mA	
Load voltage	9.7 V at 20 mA	
Impedance	485 Ω at 20 mA	

#### **DIGITAL INPUT**

Input for the following functions:

- no function
- move to 0%
- move to 100%
- hold previous position
- block local configuration
- block local configuration and operation
- block any access (local or via PC)

Binary input DI		
Terminals	+81 / -82	
Supply voltage	24 V DC (12 to 30 V DC)	
Input "logical 0"	0 to 55 V DC	
Input "logical 1"	11 to 30 V DC	
Input current	Maximum 4 mA	





## **OPTIONAL MODULES**

MODULE FOR ANALOG FEEDBACK AO *		
Terminals	+31 / -32	
Signal range	4 to 20 mA (split ranges can be parameterized)	
Supply voltage (two-wire technology)	24 V DC (11 to 30 V DC)	
Characteristic curve	Rising or falling (configurable)	
Deviation	< 1 %	

Remarks: Without any signal from the positioner (e.g. "no power", "initializing", or in the event of an error), the module sets the output to >20 mA (alarm level).

MODULE FOR DIGITAL FEEDBACK SW1, SW2 *		
Terminals	+41 / -42 and +51 / -52	
Supply voltage	5 to 11 V DC (Control circuit in accordance with DIN 19234 / NAMUR)	
Output "logical 0"	< 1.2 mA	
Output "logical 1"	> 2.1 mA	
Direction of action	Configurable "logical 0" or "logical 1"	
Description	2 software switches for binary position feedback (position adjustable within the range of 0 to 100 %, ranges cannot overlap).	

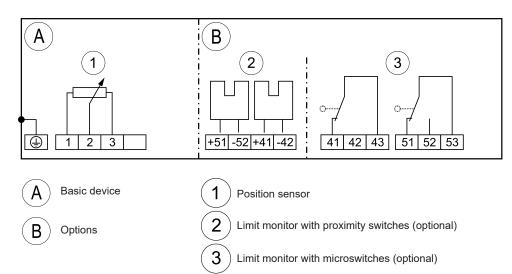
<sup>\*</sup> The module for analog feedback and the module for digital feedback have separate slots and can be used together.

**Assembly kits for limit monitor:** Two proximity switches or microswitches for independent signaling of the actuator position, switching points are adjustable between 0 to 100%

LIMIT MONITOR WITH PROXIMITY SWITCHES 1, 2				
Terminals	+41 / -42 and +51 / -52			
Supply voltage	5 to 11 V DC (Control circuit in accordance with DIN 19234 / NAMUR)			
Direction of action	Metal tag in proximity switch	Metal tag outside proximity switch		
Type SJ2-SN (NC)	< 1.2 mA	> 2.1 mA		

LIMIT MONITOR WITH 24V MICROSWITCHES 1, 2		
Terminals	+41 / -42 and +51 / -52	
Supply voltage	Maximum 24 V AC/DC	
Load rating	Maximum 2 A	
Contact surface	10 μm Gold (AU)	

## **TZIDC** Remote sensor electrical connections



TERMINALS		
TERMINAL	DESCRIPTION / CONNECTION	
1/2/3	TZIDC control unit	
+51 / -52	Proximity switches Limit 1 (optional)	
+41 / -42	Proximity switches Limit 2 (optional)	
41 / 42 / 43	Microswitches Limit 1 (optional)	
51 / 52 / 53	Microswitches Limit 2 (optional)	

Remarks: The TZIDC Remote Sensor can be fitted either with proximity switches or microswitches as limit switches. It is not possible to combine both variants.

**Remark:** For full product specifications, including requirements for use in potentially explosive atmospheres, different communication protocols (Profibus PA and FOUNDATION Fieldbus-H1) and others, please consult.

